# Best $L_{q}$ Approximate Solutions of Certain Systems of Differential Equations 

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## Introduction

For the vector $Y=\left(y_{1}, y_{2}, \ldots, y_{n}\right)$, let $\|Y\|=\sum_{i=1}^{n}\left|y_{i}\right|$. Let $\left\{E_{j}\right\}$, $j=1,2, \ldots, n$, be the canonical basis for $R^{n}$. If $Y(x)$ is the unique solution on $[0, b]$ to

$$
\begin{gather*}
L[Y] \equiv Y^{\prime}+F(x, Y)+G(x, Y)=h(x)  \tag{1}\\
Y(0)=A=\left(a_{1}, a_{2}, \ldots, a_{n}\right) \tag{2}
\end{gather*}
$$

then we consider best approximating $Y(x)$ by elements of the set

$$
\begin{equation*}
\mathscr{P}_{k}=\left\{P_{k}(x)\right\}, \tag{3}
\end{equation*}
$$

where

$$
\begin{equation*}
P_{k}(x)=A+\sum_{i=1}^{k} x^{i} \sum_{j=1}^{n} c_{i j} E_{j} \tag{4}
\end{equation*}
$$

in the sense that

$$
\begin{equation*}
\left\|h(x)-L\left[P_{k}(x)\right]\right\|_{q}=\left\{\int_{0}^{b}\left\|h(x)-L\left[P_{k}(x)\right]\right\|^{q} d x\right\}^{1 / q} \tag{5}
\end{equation*}
$$

is a minimum, $q \geqslant 1$.
In a previous paper in this journal [1], the author has considered the problem of approximating the solution to (1) and (2) (scalar case) by polynomials $p_{k}(x)$ that minimize

$$
\left\|h(x)-L\left[p_{k}(x)\right]\right\|=\sup _{0 \leqslant x \leqslant b}\left|L[y(x)]-L\left[p_{k}(x)\right]\right| .
$$

This paper is a sequel to Ref. [1]. Since the $L_{q}$ norm is being used, the analysis is, in general, different. In the case of repetitious arguments, details will be
omitted. Stein and Klopfenstein have considered a vector problem of this type; their analysis involved a linear system [4].

## The Existence of Best Approximations

Showing that there exists a "vector polynomial" in the set $\mathscr{P}_{k}$ that is the best approximation to $Y(x)$ in the sense of (5), essentially involves proving that there exists a vector $c^{*} \in S \subseteq R^{(k+1) n}, S$ closed, such that

$$
\left\|h(x)-R\left(c^{*}, x\right)\right\|_{q}=\inf _{c \in S}\|h(x)-R(c, x)\|_{q}
$$

where $R(c, x)=L\left[P_{k}(x)\right]$. Thus, the existence of a "vector polynomial" in $\mathscr{P}_{k}$ that minimizes (5) is a nonlinear best approximation problem.

In order to insure a best approximation to $Y(x)$ in sense of (5), and to insure later results, we assume that the operator $L$ satisfies the following conditions:
(i) $F$ and $G$ are elements of $C\left[I \times R^{n}, R^{n}\right]$, where $I=[0, b]$.
(ii) There exist real numbers $\alpha, \beta$ and scalar functions $u(x), \theta(Y)$, and $\mu(x, Y)$ such that, for all $r \geqslant 1$,

$$
\|G(x, Y)\| \geqslant r^{\alpha}\left\|u(x) \theta\left(\frac{Y}{r}\right)\right\|
$$

and

$$
\|F(x, Y)\| \leqslant r^{\beta}\left|\mu\left(x, \frac{Y}{r}\right)\right| ;
$$

furthermore,
(a) the function $u(x)$ is not zero almost everywhere and is $L_{q}, q \geqslant 1$.
(b) $\theta \in C\left[R^{n}, R\right]$, and $\theta(Y)=0$ if and only if $\|Y\|=0$.
(c) $\mu(x, Y) \in C\left[I \times R^{n}, R\right]$.

Scalar examples of such operators may be found in Ref. [1]. An additional example is now given. Let $Y=\left(y_{1}, y_{2}\right)$, and

$$
\begin{aligned}
L[Y] & \equiv\left[\begin{array}{l}
y_{1}^{\prime} \\
y_{2}^{\prime}
\end{array}\right]+\left[\begin{array}{l}
f_{1}(x) y_{1}+f_{2}(x) y_{2} \\
v_{1}(x) y_{1}+v_{2}(x) y_{2}+g(x)\left(\left|y_{1}\right|^{3}+y_{2}^{2}+e^{1 /\left(y_{1}{ }^{2}+1\right)}\right)
\end{array}\right] \\
& =\left[\begin{array}{l}
h_{1}(x) \\
h_{2}(x)
\end{array}\right], \quad Y(0)=\left(a_{1}, a_{2}\right)
\end{aligned}
$$

where $f_{1}, f_{2}, v_{1}, v_{2}, g, h_{1}$, and $h_{2}$ are continuous on $[0, b]$, and $g(x) \neq 0$. Then

$$
F(x, Y)=\left[\begin{array}{c}
f_{1} y_{1}+f_{2} y_{2} \\
v_{1} y_{1}+v_{2} y_{2}
\end{array}\right], \quad G(x, Y)=\left[\begin{array}{c}
0 \\
g\left(\left|y_{1}\right|^{3}+y_{2}^{2}+e^{1 /\left(y_{1}{ }^{2}+1\right)}\right)
\end{array}\right] .
$$

Thus, we may take $u(x)=g(x), \theta(Y)=\left|y_{1}\right|^{3}+y_{2}{ }^{2}, \mu(x, Y)=\|F(x, Y)\|$, $\alpha=2, \beta=1$.

We now state the principal theorem of this section.
Theorem 1. Suppose that $F$ and $G$ satisfy conditions (i) and (ii), and that $h(x) \in C\left[I, R^{n}\right]$. If $\alpha>\max (1, \beta)$, then there exists a polynomial $P_{k}{ }^{*}(x)$ in $\mathscr{P}_{k}$ such that

$$
\left\|h(x)-L\left[P_{k}^{*}(x)\right]\right\|_{q}=\inf _{P_{k} \in_{k}}\left\|h(x)-L\left[P_{k}(x)\right]\right\|_{\mathcal{q}}
$$

The proof of this theorem is similar to that of Theorem 1 of Ref. [1] and is, therefore, omitted.

## Convergence of Approximating Polynomials

Theorem 2. Suppose that $Y(x)$ is the unique solution to (1) and (2) on $[0, b]$. Further, suppose that $F, G$, and $h$ satisfy the conditions of Theorem 1 , and that $F+G$ satisfies a Lipschitz condition in $Y$ on every compact subset $S$ of $I \times R^{n}$, i.e., if $\left(x, Y_{1}\right)$ and $\left(x, Y_{2}\right) \in S$, then

$$
\left\|F\left(x, Y_{1}\right)+G\left(x, Y_{1}\right)-F\left(x, Y_{2}\right)-G\left(x, Y_{2}\right)\right\| \leqslant M_{S}\left\|Y_{1}-Y_{2}\right\| .
$$

If $\left\{P_{k}(x)\right\}$ is a sequence of vector polynomials which, for each $k$, minimize (5), then

$$
\lim _{k \rightarrow \infty}\left\|Y(x)-P_{k}(x)\right\|=0
$$

uniformly on $[0, b]$.
Proof. For notational convenience, let $F(x, Y)+G(x, Y)=T(x, Y)$. Let $Q_{k}(x) \in \mathscr{P}_{k}, k=1,2, \ldots$, be such that

$$
\begin{equation*}
\left\|Y^{(i)}(x)-Q_{k}^{(i)}(x)\right\| \leqslant \epsilon_{k}, \quad i=0,1 \tag{6}
\end{equation*}
$$

where

$$
\begin{equation*}
\lim _{k \rightarrow \infty} \epsilon_{k}=0 \tag{7}
\end{equation*}
$$

(Such $Q_{k}(x)$ are known to exist.) Then

$$
\begin{align*}
\left\|h(x)-L\left[Q_{k}(x)\right]\right\| & =\left\|Y^{\prime}-Q_{k}^{\prime}+T(x, Y)-T\left(x, Q_{k}\right)\right\| \\
& \leqslant\left\|Y^{\prime}-Q_{k}^{\prime}\right\|+\left\|T(x, Y)-T\left(x, Q_{k}\right)\right\| \\
& \leqslant \epsilon_{k}+M\left\|Y-Q_{k}\right\|  \tag{8}\\
& \leqslant \epsilon_{k}(1+M) .
\end{align*}
$$

But

$$
\left\|h(x)-L\left[P_{k}(x)\right]\right\|_{q} \leqslant\left\|h(x)-L\left[Q_{k}(x)\right]\right\|_{q}
$$

Therefore

$$
\begin{equation*}
\lim _{k \rightarrow \infty}\left\|h(x)-L\left[P_{k}(x)\right]\right\|_{q}=0 \tag{9}
\end{equation*}
$$

Let

$$
f_{k}(x)=h(x)-L\left[P_{k}(x)\right] .
$$

Then

$$
P_{k}^{\prime}+T\left(x, P_{k}\right)=h(x)-f_{k}(x)
$$

This implies that

$$
\begin{equation*}
P_{k}(x)=H_{k}(x)-\int_{0}^{x} T\left(t, P_{k}(t)\right) d t \tag{10}
\end{equation*}
$$

where

$$
H_{k}(x)=\int_{0}^{x} h(t) d t-\int_{0}^{x} f_{k}(t) d t+A
$$

From (1) we have that $Y(x)$ is the unique solution to

$$
\begin{equation*}
Y(x)=H(x)-\int_{0}^{x} T(t, Y(t)) d t \tag{11}
\end{equation*}
$$

where

$$
H(x)=\int_{0}^{x} h(t) d t+A
$$

Also

$$
\begin{equation*}
\left\|H(x)-H_{k}(x)\right\|=\left\|\int_{0}^{x} f_{k}(t) d t\right\| \tag{12}
\end{equation*}
$$

But Hölder's inequality implies that

$$
\begin{equation*}
\left\|\int_{0}^{x} f_{k}(t) d t\right\| \leqslant M\left\|f_{k}(t)\right\|_{q}, \quad \text { where } M \text { is a constant. } \tag{13}
\end{equation*}
$$

Therefore, (9) implies that

$$
\lim _{k \rightarrow \infty}\left\|\int_{0}^{x} f_{k}(t) d t\right\|=0
$$

and, consequently, by (12),

$$
\begin{equation*}
\lim _{k \rightarrow \infty}\left\|H(x)-H_{k}(x)\right\|=0 \tag{14}
\end{equation*}
$$

uniformly on $[0, b]$. Now (10), (11) and (14) suggest we consider Volterra integral equations

$$
\left(I^{*}-K^{*}\right) \phi=r_{n}
$$

and

$$
\left(I^{*}-K^{*}\right) \phi=r
$$

where $I^{*} \phi=\phi$,

$$
K^{*} \phi=\int_{0}^{x} K(x, t, \phi(t)) d t
$$

and where

$$
\lim _{n \rightarrow \infty}\left\|r_{n}(x)-r(x)\right\|=0, \quad \text { uniformly on }[0, b]
$$

Suppose that $y_{n}(x)$ is a solution to $\left(10^{\prime}\right)$ on $[0, b]$ and that $y(x)$ is the unique solution to ( $11^{\prime}$ ) on $[0, b]$. Then it can be shown that if $K \in C\left[I \times I \times R^{n}, R^{n}\right]$, $I=[0, b]$, and if, for $S \subseteq I \times I \times R^{n}, S$ compact, $(x, t, Y) \in S,(x, t, Z) \in S$, we have

$$
\|K(x, t, Y)-K(x, t, Z)\| \leqslant M_{S}\|Y-Z\|
$$

then

$$
\lim _{n \rightarrow \infty}\left\|y_{n}(x)-y(x)\right\|=0
$$

uniformly on $[0, b]$.
Applying these remarks to (10) and (11), we have

$$
\lim _{k \rightarrow \infty}\left\|Y(x)-P_{k}(x)\right\|=0
$$

uniformly on $[0, b]$.

Corollary 1. Suppose that the hypotheses of Theorem 2 are satisfied. Let $Q_{k}(x) \in \mathscr{P}_{k}, k=1,2, \ldots$, where

$$
\left\|Y^{(i)}(x)-Q_{k}^{(i)}(x)\right\| \leqslant \epsilon_{k}, \quad i=0,1
$$

and where $\lim _{k \rightarrow \infty} \epsilon_{k}=0$. If $P_{k}(x)$ is a vector polynomial of degree $k$ that minimizes (5), then

$$
\left\|Y(x)-P_{k}(x)\right\| \leqslant N \epsilon_{k} .
$$

Proof. For all $k$, Theorem 2 implies that $\left\{\left(x, P_{k}(x)\right)\right\} \subseteq S \subseteq I \times R^{n}$, where $S$ is compact. Without loss of generality we may assume that $\left\{\left(x, Q_{k}(x)\right)\right\} \subseteq S$ for all $k$. Then the argument following (7) shows that

$$
\begin{equation*}
\left\|f_{k}(x)\right\|_{\alpha} \leqslant \epsilon_{k}(1+M) . \tag{15}
\end{equation*}
$$

But Eqs. (10) and (11) imply that

$$
Y(x)-P_{k}(x)=\int_{0}^{x} f_{k}(t) d t+\int_{0}^{x} T\left(t, P_{k}(t)\right) d t-\int_{0}^{x} T(t, Y(t)) d t .
$$

Consequently

$$
\left\|Y(x)-P_{k}(x)\right\| \leqslant\|f(x)\|_{q}+\int_{0}^{x}\left\|T(t, Y(t))-T\left(t, P_{k}(t)\right)\right\| d t
$$

Therefore (15), the Lipschitz condition on $S$, and Gronwall's inequality imply that

$$
\left\|Y(x)-P_{k}(x)\right\| \leqslant N \epsilon_{k} .
$$

We note that Corollary 1 implies that if $Y^{(p)}(x)$ satisfies a Lipschitz condition on $[0, b]$, then

$$
\left\|Y(x)-P_{k}(x)\right\| \leqslant \frac{N^{*}}{k^{x}}
$$

for $k$ sufficiently large.
Corollary 2. Suppose that the hypotheses of Theorem 2 are satisfied. If $P_{k}(x)$ and $Q_{k}(x), k=1,2, \ldots$, are the vector polynomials described in Corollary 1, and if $\lim _{k \rightarrow \infty} k^{2} \epsilon_{k}=0$, then $\lim _{k \rightarrow \infty}\left\|Y^{\prime}(x)-P_{k}{ }^{\prime}(x)\right\|=0$, uniformly on $[0, b]$.

This corollary is a direct consequence of Markoff's inequality. The details of the proof are omitted.

## References

1. M. S. Henry, Best approximate solutions of nonlinear differential equations, J. Approximation Theory 3 (1970), 59-65.
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